# Obtaining soliton solutions of equations combined with the Burgers and equal width wave equations using a novel method 

Azadeh Badiepour ${ }^{1}$, Zainab Ayati $^{2}{ }^{2, *}$, and Hamideh Ebrahimi ${ }^{3}$<br>${ }^{1}$ Department of Mathematics, Guilan Science and Research Branch, Islamic Azad University, Rasht, Iran.<br>${ }^{2}$ Department of Engineering sciences, Faculty of Technology and Engineering East of Guilan, University of Guilan, Rudsar-Vajargah, Iran.<br>${ }^{3}$ Department of Mathematics, Rasht Branch, Islamic Azad University, Rasht, Iran.


#### Abstract

In the present paper, a modified simple equation method is used to obtain exact solutions of the equal width wave Burgers and modified equal width wave Burgers equations. By giving specific values to the parameters, particular solutions are obtained and the plots of solutions are drawn. It shows that the proposed method can be easily generalized to solve a variety of non-linear equations by implementing a robust and straightforward algorithm without the need for any tools.


Keywords. Simple equation method, Burgers equation, Modified equal width wave equation, Soliton solution.
2010 Mathematics Subject Classification. 35D99, 34A05.

## 1. Introduction

Many of the equations resulting from the mathematical modeling of various problems are through a nonlinear differential equation. Therefore, obtaining an analytical or approximate solution to these equations is very important. In the last decade, various methods have been introduced and used for this purpose, such as the exponential function method [5, 7, 9, 10, 12, 36, 37], Adomian decomposition method [8], Homotopy perturbation method [11], variational iteration method [13, 14], tanh method [24, 29], $G^{\prime} / G$ expansion method [30], and many others [1-4, 6, 15-17, 19, $23,25,28,33]$. One of the most important methods is the simple equation method (SE method) [18, 20-22, 26, 27, $31,32,34,35]$. The primary purpose is to extend this method for obtaining the exact solution of equal width wave Burgers (EW-Burgers) and modified equal width wave Burgers (MEW-Burgers) equations. The structure and steps of the proposed method with the help of mathematical software are quite simple.

The continuous process of the article is as follows. Section 2 describes the modified simple equation (MSE) method. In section 3, the MSE method is used to obtain the exact solution of the MEW-burgers equation. The EW-Burgers equation is discussed in section 4 . Finally, a conclusion is presented in section 5.

## 2. The MSE method

To describe the MSE method, let us consider a following nonlinear PDE

$$
\begin{equation*}
p\left(u, u_{t}, u_{x}, u_{x x}, u_{t t}, \ldots\right)=0 \tag{2.1}
\end{equation*}
$$

The implementation of this method can be divided into several stages.
Step 1. By changing the variable

Received: 10 July 2021 ; Accepted: 22 November 2021.

* Corresponding author. Email: ayati.zainab@gmail.com.

$$
\begin{equation*}
\xi=k x+w t \tag{2.2}
\end{equation*}
$$

where $w$ and $k$ are constant, Eq. (2.1) can be written as follows:

$$
\begin{equation*}
Q\left(u, u^{\prime}, u^{\prime \prime}, u^{\prime \prime \prime}, \ldots\right)=0 \tag{2.3}
\end{equation*}
$$

Step 2. In this step, we consider the following solution

$$
\begin{equation*}
u(\xi)=\sum_{i=0}^{m} a_{i}\left(\frac{F^{\prime}(\xi)}{F(\xi)}\right)^{i} \tag{2.4}
\end{equation*}
$$

where $a_{i}^{\prime} s$ are anonymous constants, $\operatorname{and} F(\xi)$ is an unknown function.
Step 3. From (2.4), we get the following results

$$
\begin{aligned}
u^{\prime}(\xi) & =m a_{m}\left(\frac{F^{\prime}(\xi)}{F(\xi)}\right)^{m-1}\left(\frac{F^{\prime \prime}}{F}-\frac{F^{\prime 2}}{F^{2}}\right)+(m-1) a_{m-1}\left(\frac{F^{\prime}(\xi)}{F(\xi)}\right)^{m-2}\left(\frac{F^{\prime \prime}}{F}-\frac{F^{2}}{F^{2}}\right)+\ldots \\
& =b_{m} \frac{F^{\prime(m+1)}(\xi)}{F^{(m+1)}(\xi)}+\frac{A(\xi)}{F^{m}(\xi)}+\ldots \\
u^{\prime \prime}(\xi) & =c_{m} \frac{F^{\prime(m+1)}(\xi)}{F^{(m+1)}(\xi)}+\frac{B(\xi)}{F^{m}(\xi)}+\ldots \\
&
\end{aligned}
$$

and

$$
u^{n}(\xi)=a_{m}{ }^{n} \frac{F^{\prime(n m)}(\xi)}{F^{(n m)}(\xi)}+\frac{B(\xi)}{F^{n m-1}(\xi)}+\cdots
$$

Therefore, the most power of $F(\xi)$ in denominator of $u^{\prime}, u^{\prime \prime}, \ldots$ is $m+1, m+2$, respectively, and this power in $u^{n}$ is equal to $n m$. To obtain the number $m$, we balance the highest derivative order and the highest nonlinear order in Eq. (2.3).

Step 4. In this step, we put Eq. (2.4) into the ordinary differential equation obtained. Therefore, a polynomial of $\frac{F^{\prime}(\xi)}{F(\xi)}$ and its derivatives will be obtained. By considering the coefficients of $F^{-i}(\xi), i=0,1,2,3, \ldots$, as zero, a system of equations that can be obtained to determine unknown constants, $F(\xi)$ and $F^{\prime}(\xi)$. Finally, solutions of Eq. (2.1) will be obtained by putting obtained results into Eq. (2.4).

## 3. Application MSE method to MEW- Bergers

In this part we use the above method for the MEW-Burgers equation as follows

$$
\begin{equation*}
u_{t}+\alpha u^{2} u_{x}+\gamma u_{x x}-\beta u_{t x x}=0 \tag{3.1}
\end{equation*}
$$

By considering (2.2), Eq. (3.1) turns to the following ODE,

$$
\begin{equation*}
w u^{\prime}+k \alpha u^{2} u^{\prime}+\gamma k^{2} u^{\prime \prime}-\beta k^{2} w u^{\prime \prime \prime}=0 \tag{3.2}
\end{equation*}
$$

We take the integrals of the both sides of equation (3.2) and set the integral to zero for constant simplicity.

$$
\begin{equation*}
w u+k \alpha \frac{u^{3}}{3}+\gamma k^{2} u^{\prime}-\beta k^{2} w u^{\prime \prime}=0 \tag{3.3}
\end{equation*}
$$

which is a special case of the second order nonlinear ordinary differential equation (2.3) obtained from the second order nonlinear partial differential equation (2.1) in [19]. In [19], if $D=-\beta k^{2} w, c_{1}-c=\gamma k^{2},-\gamma=\frac{k \alpha}{3}, \alpha=w, \beta=$ $0, A_{0}=a_{0}, A_{1}=a_{1}$, and $\Psi=F$, then the results of this manuscript about the ordinary differential equation (3.3) can be obtained from [19]. Also Eq. (3.3) is the same as the second order nonlinear ordinary differential equation (2.4) in
[17]. In [17], if $c^{2}-1=-\beta k^{2} w,-c=\gamma k^{2}, \beta=\frac{k \alpha}{3}, \alpha=w, A_{0}=a_{0}, A_{1}=a_{1}$, and $\Psi=F$, then the results of this manuscript about the ordinary differential equation (3.3) can be obtained from [17].

By balancing the order and the degree of the equation (3.3), we have $m+2=3 m$. So, we derive $m=1$. Let us assume that

$$
\begin{equation*}
u(\xi)=a_{1}\left(\frac{F^{\prime}}{F}\right)+a_{0}, \quad a_{1} \neq 0 \tag{3.4}
\end{equation*}
$$

Putting (3.4) in (3.3) and equalizing coefficient $F^{-i}(\xi), i=0,1,2,3$ to zero, leads to

$$
\begin{align*}
& w a_{0}+\frac{k \alpha}{3} a_{0}^{3}=0  \tag{3.5}\\
& -\beta k^{2} w a_{1} F^{\prime \prime \prime}+\gamma k^{2} a_{1} F^{\prime \prime}+\left(w a_{1}+k \alpha a_{0}^{2} a_{1}\right) F^{\prime}=0  \tag{3.6}\\
& 3 \beta k^{2} w a_{1} F^{\prime} F^{\prime \prime}+\left(-\gamma k^{2} a_{1}+k \alpha a_{0} a_{1}^{2}\right) F^{2}=0  \tag{3.7}\\
& \left(\frac{k \alpha}{3} a_{1}^{3}-2 \beta k^{2} w a_{1}\right)\left(F^{\prime}\right)^{3}=0 \tag{3.8}
\end{align*}
$$

From Eqs. (3.5) and (3.8) and by considering $a_{1} \neq 0$ from (3.4), we have

$$
\begin{aligned}
& a_{0}=0, \pm \sqrt{\frac{-3 w}{k \alpha}} \\
& a_{1}= \pm \sqrt{\frac{6 k w \beta}{\alpha}}
\end{aligned}
$$

Case 1: If $a_{0}=0,(3.6)$ and (3.7) change to

$$
\begin{align*}
& \left(-\beta k^{2} w F^{\prime \prime \prime}+\gamma k^{2} F^{\prime \prime}+w F^{\prime}\right) a_{1}=0,  \tag{3.9}\\
& \left(3 \beta w F^{\prime} F^{\prime \prime}-\gamma F^{2}\right) k^{2} a_{1}=0 \tag{3.10}
\end{align*}
$$

If $k=0$, then $\xi=w t$ and the solution will be obtained in $t$ which is useless. By solving Eq. (3.10), we obtain

$$
F^{\prime}=A e^{\frac{\gamma}{3 \beta w} \xi}
$$

Therefore we derive

$$
F=A \frac{3 \beta w}{\gamma} e^{\frac{1}{\beta}\left(\left( \pm \sqrt{\frac{-\beta}{2}}\right) x+\frac{\gamma}{3} t\right)}+B
$$

By placing above solution into (3.9), we derive

$$
k= \pm \frac{3 w}{\gamma} \sqrt{\frac{-\beta}{2}}
$$

By replacing $F$ and $F^{\prime}$ into Eq. (3.4), the general solution of Eq. (3.1) has been obtained as

$$
\begin{equation*}
u(x, t)= \pm \sqrt{\frac{6 k w \beta}{\alpha}}\left(\frac{A \gamma e^{\frac{1}{\beta}\left(\left( \pm \sqrt{\frac{-\beta}{2}}\right) x+\frac{\gamma}{3} t\right)}}{3 A \beta w e^{\frac{1}{\beta}\left(\left( \pm \sqrt{\frac{-\beta}{2}}\right) x+\frac{\gamma}{3} t\right)}+\gamma B}\right) \tag{3.11}
\end{equation*}
$$

The plots of above solution for $\beta=-2, \alpha=-1, w=1, \gamma=1, A=1$, and $B=1$ illustrated in Figure 1.
Case 2: If $a_{0}=+\sqrt{\frac{-3 w}{k \alpha}}$ Eqs. (3.6) and (3.7) turns to

$$
\begin{equation*}
-\beta k^{2} w F^{\prime \prime \prime}+\gamma k^{2} F^{\prime \prime}-2 w F^{\prime}=0 \tag{3.12}
\end{equation*}
$$



Figure 1. Plot of solution (3.11) for $\beta=-2, \alpha=-1, w=1, \gamma=1, \mathrm{~A}=1$ and $\mathrm{B}=1$.

$$
\begin{equation*}
3 \beta k w F^{\prime} F^{\prime \prime}+(-\gamma k \pm 3 w \sqrt{-2 \beta}) F^{2}=0 \tag{3.13}
\end{equation*}
$$

By considering Eq. (3.13), we obtain

$$
\begin{equation*}
F^{\prime}=A e^{\left(\frac{\gamma}{3 \beta w} \mp \frac{\sqrt{-2 \beta}}{\beta k}\right) \xi} \tag{3.14}
\end{equation*}
$$

where $\beta<0$ and $A$ is an arbitrary constant. Therefore, from (3.14) and (3.12), we have

$$
k= \pm \frac{3 w \sqrt{-2 \beta}}{2 \gamma}
$$

and

$$
F^{\prime}=A e^{\frac{-\gamma}{3 \beta w} \xi}
$$

So,

$$
F=\frac{3 \beta w A}{(-\gamma)} e^{e^{\frac{-\gamma}{\beta \beta w} \xi}}+B
$$

By substituting $F$ and $F^{\prime}$ into Eq. (3.4), the general solution of Eq. (3.1) has been obtained as

$$
\begin{equation*}
u(x, t)= \pm \sqrt{\frac{6 k w \beta}{\alpha}}\left(\frac{-\gamma A e^{\left(-\frac{1}{2 \beta}\right)( \pm \sqrt{-2 \beta} x+6 \gamma t)}}{3 \beta w A e^{\left(-\frac{1}{2 \beta}\right)( \pm \sqrt{-2 \beta} x+6 \gamma t)}+B}\right)+\sqrt{\frac{-3 w}{\alpha k}} \tag{3.15}
\end{equation*}
$$

The plots of above solution for $\beta=-2, \alpha=-1, w=1, \gamma=1, A=1$, and $B=1$ illustrated in Figure 2 .
Case 3: When $a_{0}=-\sqrt{\frac{-3 w}{k \alpha}}$, the following solutions have been obtained by performing a process similar to case 2 .

$$
\begin{equation*}
u(x, t)= \pm \sqrt{\frac{6 k w \beta}{\alpha}}\left(\frac{-\gamma A e^{\left(-\frac{1}{2 \beta}\right)(\mp \sqrt{-2 \beta} x+6 \gamma t)}}{3 \beta w A e^{\left(-\frac{1}{2 \beta}\right)(\mp \sqrt{-2 \beta} x+6 \gamma t)}+B}\right)-\sqrt{\frac{-3 w}{\alpha k}} . \tag{3.16}
\end{equation*}
$$

The plots of above solution for $\beta=-2, \alpha=-1, w=1, \gamma=1, A=1$, and $B=1$ illustrated in Figure 3 .


Figure 2. Plot of solution (3.15) for $\beta=-2, \alpha=-1, w=1, \gamma=1, \mathrm{~A}=1$ and $\mathrm{B}=1$.



Figure 3. Plot of solution (3.16) for $\beta=-2, \alpha=-1, w=1, \gamma=1, \mathrm{~A}=1$ and $\mathrm{B}=1$.

## 4. Application MSE method to EW- Bergers

Let's consider the following EW-Berger equation,

$$
\begin{equation*}
u_{t}+\alpha u u_{x}-\delta u_{x x}-\mu u_{x x t}=0 . \tag{4.1}
\end{equation*}
$$

Using (2.2), it has been result

$$
\begin{equation*}
w U^{\prime}+\alpha k U U^{\prime}-k^{2} \delta U^{\prime \prime}-k^{2} w \mu U^{\prime \prime \prime}=0 \tag{4.2}
\end{equation*}
$$

Integrating (4.2) with respect $\xi$, leads to

$$
\begin{equation*}
w U+\alpha k \frac{U^{2}}{2}-k^{2} \delta U^{\prime}-k^{2} w \mu U^{\prime \prime}=0 \tag{4.3}
\end{equation*}
$$

Presumably $u(\xi)$ can be illustrated in the form (2.4). Balancing $U^{\prime \prime}$ and $U^{2}$ leads to $m+2=2 m$. So $m=2$. Let us assume that

$$
\begin{equation*}
u(\xi)=a_{2}\left(\frac{F^{\prime}}{F}\right)^{2}+a_{1}\left(\frac{F^{\prime}}{F}\right)+a_{0}, \quad a_{2} \neq 0 \tag{4.4}
\end{equation*}
$$

Putting (4.4) in (4.3) and equalizing coefficient $F^{-i}(\xi), i=0,1,2,3$, 4to zero, leads to

$$
\begin{align*}
& \frac{\alpha k}{2} a_{0}^{2}+\mathrm{w} a_{0}=0  \tag{4.5}\\
& -\mu k^{2} w a_{1} F^{\prime \prime \prime}-\delta k^{2} a_{1} F^{\prime \prime}+\left(\alpha k a_{0} a_{1}+w a_{1}\right) F^{\prime}=0  \tag{4.6}\\
& -\mu k^{2} w a_{2} F^{\prime \prime 2}+\left(-2 \delta k^{2} a_{2}-\mu k^{2} w\left(2 a_{2}-3 a_{1}\right)\right) F^{\prime} F^{\prime \prime}+\left(w a_{2}+\frac{\alpha k}{2} a_{1}^{2}+\alpha k a_{0} a_{2}+\delta k^{2} a_{1}\right) F^{2}=0  \tag{4.7}\\
& 10 \mu k^{2} w a_{2} F^{\prime 2} F^{\prime \prime}+\left(-2 a_{1} \mu k^{2} w+\alpha k a_{1} a_{2}+2 \delta k^{2} a_{2}\right) F^{\prime 3}=0  \tag{4.8}\\
& \left(\frac{\alpha k}{2} a_{2}^{2}-6 \mu k^{2} w a_{2}\right)\left(F^{\prime}\right)^{4}=0 \tag{4.9}
\end{align*}
$$

By solving Eqs. (4.5) and (4.9) and by considering $a_{2} \neq 0$ from (4.4), we drive

$$
a_{0}=0, \frac{-2 w}{\alpha k}, a_{2}=\frac{12 \mu k w}{\alpha}
$$

Case 1:
If $a_{0}=0$,and $a_{2}=\frac{12 \mu k w}{\alpha}$ Eqs. (4.6), (4.7), and (4.8) yield to

$$
\begin{align*}
& -\mu k^{2} w a_{1} F^{\prime \prime \prime}-\delta k^{2} a_{1} F^{\prime \prime}+w a_{1} F^{\prime}=0  \tag{4.10}\\
& -\frac{12 \mu^{2} k^{3} w^{2}}{\alpha} F^{\prime \prime 2}+\left(\frac{-24 \delta k^{3} \mu w}{\alpha}-\mu k^{2} w\left(\frac{24 k \mu w}{\alpha}-3 a_{1}\right)\right) F^{\prime} F^{\prime \prime}+\left(\frac{12 \mu k w^{2}}{\alpha}+\frac{\alpha k}{2} a_{1}^{2}+\delta k^{2} a_{1}\right) F^{2}=0,  \tag{4.11}\\
& \frac{120 \mu^{2} k^{3} w^{2}}{\alpha} a_{2} F^{\prime 2} F^{\prime \prime}+\left(-2 a_{1} \mu k^{2} w+12 \mu k^{2} w a_{1}+24 \frac{\mu \delta k^{3} w}{\alpha}\right) F^{\prime 3}=0 \tag{4.12}
\end{align*}
$$

By solving Eq. (4.12), we obtain

$$
\begin{equation*}
F^{\prime}=A e^{-\frac{5 \alpha a_{1}+12 \delta k}{60 w k \mu} \xi} \tag{4.13}
\end{equation*}
$$

where $A$ is an arbitrary constant. By substituting (4.13) into Eqs. (4.10) and (4.11), we get

$$
\begin{aligned}
& 60 \mu w^{2}-7 \delta k a_{1} \alpha-\frac{5}{12} a_{1}^{2} \alpha^{2}-\frac{72}{5} \delta^{2} k^{2}=0 \\
& 12 \mu k^{2} w-\frac{25}{12} k a_{1}^{2} \alpha^{2}+\frac{14}{5} a_{1} \alpha \delta k^{2}+\frac{108}{25} \delta^{2} k^{3}+2 \mu k^{2} w a_{1} \alpha+\frac{24}{5} \mu k^{3} w \delta=0
\end{aligned}
$$

By solving the above equation, we derive

$$
a_{1}=\frac{1}{\alpha}\left(-\frac{42}{5} \delta k \pm 6 \sqrt{\delta^{2} k^{2}+4 \mu w^{2}}\right) .
$$

Therefore, we have

$$
F=-A \frac{60 w k \mu}{5 \alpha a_{1}+12 \delta k} e^{-\frac{5 \alpha a_{1}+12 \delta k}{60 w k \mu} \xi}+B
$$

Replacing $F$ and $F^{\prime}$ into Eq. (4.4), the general solution of Eq. (4.1) has been obtained

$$
\begin{equation*}
u(\xi)=\frac{12 \mu k w}{\alpha}\left(\frac{A e^{-\frac{5 \alpha a_{1}+12 \delta k}{60 w \mu} \xi}}{-A_{\frac{60 w \mu}{5 \alpha a_{1}+12 \delta k} e^{-\frac{5 \alpha \alpha_{1}+12 \delta k}{60 w k \mu}}+B}^{60}}\right)^{2}+a_{1}\left(\frac{A e^{-\frac{5 \alpha a_{1}+12 \delta k}{60 w k \mu} \xi}}{-A_{\frac{60 w k \mu}{5 \alpha a_{1}+12 \delta k} e^{-\frac{5 \alpha a_{1}+12 \delta k}{60 w k \mu}}+B}^{60 w}}\right) . \tag{4.14}
\end{equation*}
$$



Figure 4. Plot of solution (4.15) for $\mathrm{A}=1$ and $\mathrm{B}=1$.


Figure 5. Plot of solution (4.15) for $\mathrm{A}=1$ and $\mathrm{B}=-1$.

By considering $\alpha=\delta=\mu=k=1$, we get $w=1.0625, a_{1}=5.6912, a_{2}=12.75$, and $w=-0.7498, a_{1}=$ $2.4143, a_{2}=-8.9972$. So we derive the following exact solutions

$$
\begin{equation*}
u(\xi)=12.75\left(\frac{A e^{-0.6346(x+1.0625 t)}}{-1.5758 A e^{-0.6346(x+1.0625 t)}+B}\right)^{2}+5.6912\left(\frac{A e^{-0.6346(x+1.0625 t)}}{-1.5758 A e^{-0.6346(x+1.0625 t)}+B}\right) \tag{4.15}
\end{equation*}
$$

and

$$
\begin{equation*}
u(\xi)=-8.9972\left(\frac{A e^{0.5351(x-0.7498 t)}}{1.8688 A e^{0.5351(x-0.7498 t)}+B}\right)^{2}+2.4143\left(\frac{A e^{0.5351(x-0.7498 t)}}{1.8688 A e^{0.5351(x-0.7498 t)}+B}\right) \tag{4.16}
\end{equation*}
$$

The plots of solutions (4.15) and (4.16) for $A=1$ and $B=1,-1$ illustrated in Figures 4-7.
Case 2: When $a_{0}=\frac{-2 w}{\alpha k}$, and $a_{2}=\frac{12 \mu k w}{\alpha}$ Eqs. (4.6), (4.7), and (4.8) yield to

$$
-\mu k^{2} w a_{1} F^{\prime \prime \prime}-\delta k^{2} a_{1} F^{\prime \prime}-w a_{1} F^{\prime}=0
$$

$$
-\frac{12 \mu^{2} k^{3} w^{2}}{\alpha} F^{\prime \prime 2}+\left(\frac{-24 \delta k^{3} \mu w}{\alpha}-\mu k^{2} w\left(\frac{24 k \mu w}{\alpha}-3 a_{1}\right)\right) F^{\prime} F^{\prime \prime}+\left(\frac{12 \mu k w^{2}}{\alpha}+\frac{\alpha k}{2} a_{1}^{2}+\delta k^{2} a_{1}-\frac{24 k \mu w^{2}}{\alpha}\right) F^{\prime 2}=0,
$$



Figure 6. Plot of solution (4.16) for $\mathrm{A}=1$ and $\mathrm{B}=1$.


Figure 7. Plot of solution (4.16) for $\mathrm{A}=1$ and $\mathrm{B}=-1$.

$$
\frac{120 \mu^{2} k^{3} w^{2}}{\alpha} a_{2} F^{\prime 2} F^{\prime \prime}+\left(-2 a_{1} \mu k^{2} w+12 \mu k^{2} w a_{1}+24 \frac{\mu \delta k^{3} w}{\alpha}\right) F^{\prime 3}=0
$$

The following results are obtained by performing a process similar to case 1 .

$$
\begin{equation*}
u(\xi)=\frac{12 \mu k w}{\alpha}\left(\frac{A e^{-\frac{5 \alpha a_{1}+12 \delta k}{60 w k \mu}} \xi}{-A \frac{60 w k \mu}{5 \alpha a_{1}+12 \delta k} e^{-\frac{5 \alpha a_{1}+12 \delta k}{60 w k \mu} \xi}+B}\right)^{2}+a_{1}\left(\frac{A e^{-\frac{5 \alpha a_{1}+12 \delta k}{60 w k \mu} \xi}}{-A \frac{60 w k \mu}{5 \alpha a_{1}+12 \delta k} e^{-\frac{5 \alpha a_{1}+12 \delta k}{60 w k \mu}}+B}\right)-\frac{2 w}{\alpha k}, \tag{4.17}
\end{equation*}
$$

where $a_{1}=\frac{1}{\alpha}\left(-\frac{42}{5} \delta k \pm 6 \sqrt{\delta^{2} k^{2}-4 \mu w^{2}}\right)$.
By considering $\alpha=\delta=\mu=k=1$, we derive $w=0.5702, a_{1}=-2.7035, a_{2}=6.8424$, and $w=-0.0975, a_{1}=$ $-14.096, a_{2}=-1.17$.

So we derive the following exact solutions

$$
\begin{equation*}
u(\xi)=6.8424\left(\frac{A e^{0.0444(x+0.5702 t)}}{22.5225 A e^{0.0444(x+0.5702 t)}+B}\right)^{2}-2.7035\left(\frac{A e^{0.0444(x+0.5702 t)}}{22.522 A e^{0.0444(x+0.5702 t)}+B}\right)-1.1404 \tag{4.18}
\end{equation*}
$$

and

$$
\begin{equation*}
u(\xi)=-1.17\left(\frac{A e^{-9.9966(x-0.0975 t)}}{-0.1 A e^{-9.9966(x-0.0975 t)}+B}\right)^{2}-14.096\left(\frac{A e^{-9.9966(x-0.0975 t)}}{-0.1 A e^{-9.9966(x-0.0975 t)}+B}\right)+0.195 \tag{4.19}
\end{equation*}
$$

Fig. 8. plots of solution (38) for $A=1, B=1$


Figure 8. Plot of solution (4.18) for $\mathrm{A}=1$ and $\mathrm{B}=1$.


Figure 9. Plot of solution (4.19) for $\mathrm{A}=1$ and $\mathrm{B}=-1$.

The plots of solutions (4.18) and (4.19) for $A=1$ and $B=1,-1$ illustrated in Figures 8 and 9.

## 5. CONCLUSION

In the current research, a well-known and useful method was applied to search the exact solutions of two NPDE and the new solutions of these equations were obtained. The outcomes indicated that the modified simple equation method was a powerful method for solving nonlinear evolution equations. It should be mentioned that this prevalent method can be algorithmically generalized to solve all kinds of nonlinear equations. The primary merits of procedure used in this research over other analytical methods was that for $F(\xi)$ there was no condition to be fulfilled. So, the probability to get new and varied solutions using this method increased outstandingly.

## References

[1] A. Akbulut, F. Taşcan, and M. Ghahremani, On symmetries, conservation laws and exact solutions of the nonlinear Schrödinger-Hirota equation, Waves in Random and Complex Media, 28(2) (2017), 389-398.
[2] M. N. Alam and C. Tunç, Constructions of the optical solitons and others soliton to the conformable fractional Zakharov-Kuznetsov equation with power law nonlinearity, Journal of Taibah University for Science, 14(1) (2020), 94-100.
[3] M. N. Alam and C. Tunç, New solitary wave structures to the (2+1)-dimensional KD and KP equations with spatio-temporal dispersion, Journal of King Saud University Science, 32 (2020), 3400-3409.
[4] M. N. Alam and C. Tunç, The new solitary wave structures for the (2+1)-dimensional time-fractional Schrodinger equation and the space-time nonlinear conformable fractional Bogoyavlenskii equations, Alexandria Engineering Journal, 59 (2020), 2221—2232.
[5] H. A. Ali, Application of He's Exp-function method and semi-inverse variational principle to equal width wave ( $E W$ ) and modified equal width wave (MEW) equations, International Journal of the Physical Sciences, 7 (2012), Doi: 10.5897/IJPS11.1755.
[6] A. Bekir, M. S. M. Shehata, and E. H. M. Zahran, New optical soliton solutions for the thin-film ferroelectric materials equation instead of the numerical solution, Computational Methods for Differential Equations, (2021), Doi: 10.22034/CMDE.2020.38121.1677.
[7] J. Biazar and Z. ayati , Application of Exp-function method to EW Burgers equation, Numer. Meth. for Part. Diff. Eq., 26(6) (2010), 1476-1482.
[8] J.Biazar, E. Babolian, A. Nouri, and R. Islam, An alternate algorithm for computing Adomian Decomposition method in special cases, App. Math. and Comput., 38(2-3) (2003), 523-529.
[9] Ebaid, Exact solitary wave solutions for some nonlinear evolution equations via Exp-function method, Phys.Lett. A, 365 (2007), 213-219.
[10] S. A. El-Wakil, Application of Exp-function method for nonlinear evolution equations with variable coefficients, Phy. Lett. A, 369(1-2) (2007), 62-69.
[11] J. H. He, Application of homotopy perturbation method to nonlinear wave equations, Chaos Solitons Fractals, 26 (2005), 695-700.
[12] J. H. He and X. H. Wu, Exp-function method for nonlinear wave equations, Chaos Solitons Fractals,30 (2006), 700-708.
[13] J. H. He, Variational iteration method-a kind of non-linear analytical technique: some examples, Int. J. Nonlinear Mech., 34 (1999), 699-708.
[14] J. H. He, Variational iteration method for autonomous ordinary differential systems, Appl. Math. Comput. 114 (2000), 115-123.
[15] M. Ilie, J. Biazar, and Z. Ayati, Resonant solitons to the nonlinear Schrödinger equation with different forms of nonlinearities, Optik, 164 (2018), 201-209.
[16] R. Islam, K. Khan, M. A. Akbar, Md. Ekramul Islam, and Md. Tanjir Ahmed, Traveling wave solutions of some nonlinear evolution equations, Alexandria Engineering Journal, 54(2) (2015), 263-269.
[17] Sh. Islam, Md. Nur Alam, Md. Fayz Al-Asad, and C. Tunç, An analytical technique for solving new computational of the modified Zakharov- Kuznetsov equation arising in electrical engineering, J. Appl. Comput. Mech, 7(2) (2021), 715-726.
[18] A. J. M. Jawad, M. D. Petkovic, and A. Biswas, Modified simple equation method for nonlinear evolution equations, Appl. Math. Comput., 217 (2010), 869-877.
[19] S. B. Karakoc and K. Karam Ali, New exact solutions and numerical approximations of the generalized KdV equation, Computational Methods for Differential Equations, 9(3) (2021), 670-691.
[20] K. Khan and M. Ali Akbar, Exact solutions of the (2+1)-dimensional cubic Klein-Gordon equation and the (3+1)dimensional Zakharov-Kuznetsov equation using the modified simple equation method, Journal of the Association of Arab Universities for Basic and Applied Sciences, 15(1) (2013).
[21] K. khan and M. Ali Akbar, Exact and solitary wave solutions for the Tzitzeica-Dodd-Bullough and the modified Kdv-Zakharov-Kuznetsov equations using the modified simple equation method, Ain Shams Engineering Journal,

4(4) (2013), 903-909.
[22] N. A. Kudryashov and N. B. Loguinova, Extended simplest equation method for nonlinear differential equations, App. Math. Comput., 205 (2008), 396-402.
[23] M. Lakestani, J. Manafian, A. R. Najafizadeh, and M. Partohaghighi, Some new soliton solutions for the nonlinear the fifth-order integrable equations, Computational Methods for Differential Equations, (2021), In press. Doi: 10.22034/CMDE.2020.30833.1462.
[24] W. Malfliet and w. Hereman, The tanh method: I. Exact solutions of nonlinear evolution and wave equations, Phys. Scr., 54 (1996), 563-8.
[25] S. N. Neossi Nguetchue, Axisymmetric spreading of a thin power-law fluid under gravity on a horizontal plane, Nonlinear Dynamics, 52(4) (2008), 361-366.
[26] N. Taghizadeh, M. Mirzazadeh, A. Samiei Paghaleh, and J. Vahidi, Exact solutions of nonlinear evolution equations by using the modified simple equation method, Ain Shams Engineering Journal, 3 (2012), 321— 325.
[27] K. Vitanov Nikolay, Modified method of simplest equation:powerful tool for obtaining exact and approximate traveling-wave solutions of nonlinear PDEs, Commun. Nonlinear Sci. Numer. Simulat., 16(2011), 1176-85.
[28] K. Wang and G. Wang. Variational principle, solitary and periodic wave solutions of the fractal modified equal width equation in plasma physics, Fractals, 29(05) (2021).
[29] A. M. Wazwaz, The tanh method: Exact solutions of the Sine-Gordon and Sinh- Gordon equations, Appl. Math. Comput., 167 (2005), 1196-1210.
[30] M. E. Zayed Elsayed and A. Amer Yasser, "Exact solutions for the nonlinear KPP equation by using the Riccati equation method combined with the $G / G$ - expansion method, Scientific Research and Essays, 10(3) (2015), 86-96.
[31] E. M. E. Zayed, A note on the modified simple equation method applied to Sharma-Tasso-Olver equation, Appl. Math. Comput., 218 (2011), 3962-3964.
[32] E. M. E. Zayed and S. A. H. Ibrahim, Exact solutions of nonlinear evolution equations in mathematical physics using the modified simple equation method, Chinese Phys. Lett., 29(6) (2012).
[33] M. E. Zayed Elsayed and A.-Gh. Al-Nowehy, Solitons and other exact solutions for variant nonlinear Boussinesq equations, Optik - International Journal for Light and Electron Optics, 139 (2017), 166-177.
[34] E. M. E. Zayed, The modified simple equation method for two nonlinear PDEs with power law and Kerr law nonlinearity, Pan Amer. Math. Journal, International Publications, USA, 24(1) (2014), 65-74.
[35] E. M. E. Zayed, The modified simple equation method applied to nonlinear two models of diffusion-reaction equations, Jour. of Math. Research and Applicat., 2(2) (2014), 5-13.
[36] S. Zhang, Application of Exp-function method to a KdV equation with variable coefficients, Phys. Lett. A, 365 (2007), 448-453.
[37] S. D. Zhu, Exp-function method for the discrete mKdV lattice, Int. J. Nonlinear Sci. Numer. Simul., 8 (2007), 465-469.

